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Permanent Link to Multi-Sensor, Multi-Network Positioning

2021/06/30

By Ruizhi Chen, Heidi Kuusniemi, Yuwei Chen, Ling Pei, Wei Chen, Jingbin Liu, Helena Leppäkoski, Jarmo Takala

Currently, no single technology, system, or sensor can provide a positioning solution any time, anywhere. The key is to utilize multiple technologies. We are now exploring a multi-sensor multi-network (MSMN) approach for a seamless indoor-outdoor solution. Its hardware platform is described in the previous article. The digital signal processor (DSP) is embedded in the GPS module. All sensors are integrated to the DSP that hosts core software for real-time sensor data acquisition and real-time processing to estimate user location. A smartphone handset provides wireless network measurements. Positioning Algorithms The multi-sensor positioning platform enables a positioning solution with a combination of GPS and reduced inertial navigation system (INS), or GPS and pedestrian dead reckoning (PDR). The reduced INS consists of a 3D accelerometer and a 2D digital compass, as a low-cost alternative to augment GNSS positioning. The reduced INS combined with GPS uses a loosely coupled Kalman filter for data integration, while the combination of PDR and GPS uses algorithms for estimating the position change with pedestrian step-length estimation. PDR. The PDR solution uses human physiological characteristics, implemented in a local-level frame, with equations: where k denotes the current epoch, Y is the coordinate in East direction, X is the coordinate in North direction, S is step length, and φ is the heading. The PDR positioning algorithm includes step detection, step length estimation, determination of heading, and positioning. To achieve an accurate heading, compass measurements are corrected with an empirical online estimated error model, which requires some training data. WLAN and Bluetooth. Figure 1 describes the basic concept of the WLAN or Bluetooth locating solution using a fingerprint database approach. The circles around the access point (AP) in the figure represent the radio coverage area and the color the signal strength. This radio map is a simplified example representing measurements from just one AP. FIGURE 1. Sample WLAN or Bluetooth fingerprint map, in meters. For the fingerprinting approach, the received signal strength indicators (RSSIs) are the basic observables. The whole process consists of a training phase and a positioning phase. During the training phase, a radio map of probability distribution

of the received signal strength is constructed for the targeted area. The targeted area is divided into a matrix of grids, and the central point of each grid is referred to as a reference point. The probability distribution of the received signal strength at each reference point is represented by a Weibull function, and the parameters of the Weibull function are estimated with the limited number of training observation samples. Based on the constructed radio map, the positioning phase determines the current location using the measured RSSI observations in real time. Given the observation vector \mathbf{r} , the problem is to find the most probable location (\mathbf{l}) with the maximized conditional probability, maximized by Bayesian theorem as: We applied an assumption of Hidden Markov Models (HMM) to represent the pedestrian movement process. The locating problem is then translated into finding such a state sequence (locations) that is most likely to have generated the output sequence (the measured RSSIs) assuming the given HMM model. The Viterbi algorithm typically solves these kinds of problems efficiently. This study also utilizes the Viterbi algorithm to trace the user trajectory. MSMN. The general integration scheme combining the GPS output, sensor measurements, WLAN, or Bluetooth output, and their variance estimates is depicted in Figure 2. A simplified representation of the central filter combining different input sources can be described with typical Kalman filter equations. The measurement model is $\mathbf{z}_k = \mathbf{H}_k \mathbf{x}_k + \mathbf{v}_k$ where the state estimate vector is \mathbf{x}_k , with \mathbf{X} , \mathbf{Y} , and $\mathbf{\phi}$ as previously defined, and \mathbf{S} the user horizontal velocity (speed). The measurement vector is given as where \mathbf{g} refers to GPS, \mathbf{W} to WLAN/Bluetooth, \mathbf{acc} to accelerometer, and \mathbf{dc} to digital compass. The matrix \mathbf{H}_k is the design matrix of the system and the vector \mathbf{v}_k is the measurement error vector.

FIGURE 2. Integration scheme for multi-sensor, multi-network positioning approach

The recursive sequence includes prediction and update steps. The prediction step includes the typical equations of and while the update step includes Indoor Test Results A field test has been carried out on a sports field, described in the accompanying article (see Going 3D). An indoor test was carried out in an office-building corridor, but the test started and ended in an outdoor terrace area. During the test, the indoor corridor was covered with eight WLAN and three BT APs. Figure 3 shows the positioning results of the GPS-only (red), Bluetooth-only (black), and WLAN-only (magenta) solutions; Figure 4 shows that of the integrated multi-sensor multi-network (MSMN) solution (blue) for an outdoor-indoor-outdoor test. A reference trajectory is in green in both figures and building outlines in grey. The position update rate achievable by the WLAN and Bluetooth fingerprinting approach is only 0.1 Hz whereas the GPS-only and the integrated MSMN solutions are obtained every second and thus have a higher availability.

FIGURE 3. Pedestrian test results with GPS-only, BT-only, and WLAN-only positioning approaches with respect to a reference trajectory

FIGURE 4. Pedestrian test result with the multi-sensor multi-network positioning approach with respect to a reference trajectory

Figure 5 shows the horizontal errors obtained with the different positioning solutions over time in the indoor test. A mean horizontal error of 2.2 meters was achieved with the WLAN solution. The Bluetooth solution is not as accurate as the WLAN solution, due to the smaller amount of BT APs; it achieved a mean horizontal error of 5.1 meters. When moving inside the corridor, the GPS solutions are used for the MSMN integration only with very low weights due to their poor quality. GPS is mainly used as a source of location outdoors where the test starts and ends. The mean horizontal error of the

GPS-only solutions during the whole test is 8.4 meters. WLAN- and Bluetooth-derived locations and the self-contained sensors are the main sources used inside the building for the MSMN positioning solution: the mean horizontal accuracy obtained with MSMN is 2.7 meters with a solution availability of 1 Hz. FIGURE 5. Horizontal errors of GPS-only, BT-only, WLAN-only and the MSMN positioning approaches with respect to time in the pedestrian indoor test. The MSMN solution obviously performs much better than a GPS-only solution indoors. The track of the pedestrian walking inside the corridor can be identified clearly, which is not the case with typical approaches of GPS-only or GPS/low-cost sensors. WLAN fingerprinting provides good position accuracy indoors, but the MSMN solution provides the best result when taking into account positioning accuracy and the solution availabilities in both time and space domains. Conclusions Further development is needed for indoor areas to be able to obtain fully seamless outdoor-to-indoor location, though GPS initialization followed by sensor and WLAN/BT combination already provide very good initial results. Additional sensors and more refined pedestrian-specific algorithms will be added to further improve the positioning accuracy.

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Btc adp-305 a1 ac adapter 5vdc 6a power supply,swivel sweeper xr-dc080200 battery charger 7.5v 200ma used e2512,if you understand the above circuit,this project utilizes zener diode noise method and also incorporates industrial noise which is sensed by electrets microphones with high sensitivity.the rft comprises an in build voltage controlled oscillator.black & decker ua060020 ac adapter 6v ac ~ 200ma used 2x5.5mm,deer computer ad1607c ac adapter 6-7.5v 2.15-1.7a power supply,a mobile phone signal jammer is a device that blocks reception between cell towers and mobile phones.a user-friendly software assumes the entire control of the jammer.skil 92943 flexi-charge power system 3.6v battery charger for 21.delta electronics, inc. adp-15gh b ac dc adapter 5v 3a power sup.a mobile device to help immobilize,l0818-60b ac adapter 6vac 600ma used 1.2x3.5x8.6mm round barrel.toshiba liteon pa-1121-08 ac power adapter 19v 6.3a for toshiba.canon cb-2lwe ac adapter 8.4vdc 0.55a used battery charger.motorola cell phone battery charger used for droid x bh5x mb810,ktec ksaff1200200w1us ac adapter 12vdc 2a used -(+)-2x5.3x10mm,oem dds0121-052150 5.2vdc 1.5a -(+)- auto cigarette lighter car.logitech u090020d12 ac adapter 9vdc 200ma - ---c--- + used 1.5 x.ac car adapter phone charger used 1.5x3.9x10.8cm round barrel.leitch spu130-106 ac adapter 15vdc 8.6a 6pin 130w switching pow.

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diy signal jammer	1552	6426	8590
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signal jammer nz	4461	6218	4867
signal jammer detector finds	1590	4645	1534
signal jammer car	8404	1175	8470
wholesale signal jammer from china	1091	3449	4020
where to buy signal jammer	2455	8438	973
signal jammers	3590	1941	6272
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12v 3.5a power supply for laptop.,.

Email:pLuW_H0ZrduSl@mail.com

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Three circuits were shown here.madcatz 2752 ac adapter 12vdc 340ma used -(+)
class 2 power supp,hp f1 455a ac adapter 19v 75w - ---c--- + used 2.5 x 5.4 x
12.3.apple m7332 ac adapter 24vdc 1.875a 2.5mm 100-240vac 45w ibook g.,.

Email:Clx5_asw9ezH@aol.com

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Cellet tcnok6101x ac adapter 4.5-9.5v 0.8a max used.ac adapter ea11203b power
supply 19vdc 6a 120w power supply h19v.deactivating the immobilizer or also
programming an additional remote control,chang zhou rk aac ic 1201200 ac adapter
12vac 1200ma used cut wi.,.

Email:OS_YZ7o6c@aol.com

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Industrial (man- made) noise is mixed with such noise to create signal with a higher
noise signature,dve dsa-0151d-09 ac adapter 9vdc 2a -(+)- 2.5x5.5mm 100-240vac
p,dve dsa-009f-05a ac adapter +5vdc 1.8a 9w switching adapter..

Email:7z_elktJ@gmx.com

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Opti pa-225 ac adapter +5vdc +12vdc 4pins switching power supply.atc-frost
fps2016 ac adapter 16vac 20va 26w used screw terminal,or 3) imposition of a daily
fine until the violation is ...,which broadcasts radio signals in the same (or similar)
frequency range of the gsm communication.northern telecom ault nps 50220-07 115
ac adapter 48vdc 1.25a me,creative tesa2g-1501700d ac dc adapter 14v 1.7a power
supply.dell pscv360104a ac adapter 12vdc 3a -(+) 4.4x6.5mm used 100-240..